

II The general linear programming problem LP

$$\max f(\mathbf{x}) = \mathbf{c}^T \mathbf{x}$$

under the constraints:

$$\begin{aligned} \mathbf{A}_1 \mathbf{x} &\leq \mathbf{b}_1 \\ \mathbf{A}_2 \mathbf{x} &\geq \mathbf{b}_2 \\ \mathbf{x} &\geq 0 \end{aligned}$$

$$\dim \mathbf{x} = [n \times 1], \dim \mathbf{c} = [n \times 1]$$

Matrices $\mathbf{A}_1, \mathbf{A}_2$:

$$\dim \mathbf{A}_1 = [m_1 \times n], \dim \mathbf{A}_2 = [m_2 \times n]$$

Vectors $\mathbf{b}_1, \mathbf{b}_2$:

$$\dim \mathbf{b}_1 = [m_1 \times 1], \dim \mathbf{b}_2 = [m_2 \times 1]$$

The general linear programming problem LP

Two phase simplex method

I phase - it is necessary to find a first basic, admissible solution by solving the auxiliary problem with an auxiliary objective function

II phase - maximization of an objective function x_0 with the simplex method.

Step 1. (start). Let us find first basic, admissible solution.

The permissibility condition: if $y_{i0} \geq 0$ for $i = 1, \dots, m$

Yes - go to **Step 2**, No - **STOP**.

I phase - it is necessary to find a first basic, admissible solution by solving the auxiliary problem with an auxiliary objective function

•The initial non - admissible simplex table can be transformed to the permissible form with the help of the simplex method.

•Aim - to obtain non negative values of auxiliary variables.

•It is necessary to determine a minimal value:

$$s \Rightarrow \min \{y_{i0}, y_{i0} < 0 \text{ dla } i = 1, 2, \dots, m\}$$

•The variable s will be the auxiliary objective function, which will be maximized.

•I phase is realised till the permissible condition will be fulfilled:

$$y_{i0} \geq 0 \text{ dla } i = 1, 2, \dots, m$$

•The end of I phase

Example III for linear programming problem two phase simplex method

$$\max_{x \in X} x_0 = 1x_1 + 6x_2$$

$$X = \left\{ \begin{aligned} &+2x_1 + 1x_2 \geq 2 \\ &x_1 - 1x_1 + 1x_2 \leq 3, x \geq 0 \\ &+1x_1 + 1x_2 \leq 6 \end{aligned} \right\}$$

I phase

	$-x_1$	$-x_2$
x_0	0	-1
x_1	-2	-2
x_2	3	-1
$-x_3$	6	1

The table is not admissible

II phase part.1

	$-x_3$	$-x_4$
x_0	6	1
x_1	10	2
$-x_2$	9	1
x_1	6	1

I basic admissible solution

$$x_0 = \begin{bmatrix} 6 \\ 0 \end{bmatrix}, x_0^0 = 6$$

II phase part.2

	$-x_3$	$-x_4$
x_0	28.5	3.5
x_1	5.5	1.5
x_2	4.5	0.5
x_1	1.5	0.5

II basic admissible solution - optimal solution

$$x_0 = \begin{bmatrix} 15 \\ 4.5 \end{bmatrix}, x_0^0 = 28.5$$

Optimal solution: $\hat{x} = \begin{bmatrix} x_1^0 \\ x_2^0 \\ x_3^0 \\ x_4^0 \end{bmatrix} = [1.5 \ 4.5 \ 0 \ 0]^T, \hat{x}_0 = 28.5$

III The linear programming problem LP for real variables

$$\max f(\mathbf{x}) = \mathbf{c}^T \mathbf{x}$$

under the constraints:

$$\begin{aligned} \mathbf{A}_1 \mathbf{x} &\leq \mathbf{b}_1 \\ \mathbf{A}_2 \mathbf{x} &\geq \mathbf{b}_2 \\ \mathbf{x}_1 &\in R, \mathbf{x}_2 \geq 0 \end{aligned}$$

It is necessary to use the additional variable in the form: $\mathbf{x}_i = x_i' - x_i''$

$$\begin{aligned} \min_{x \in X} x_0 = x_1 + x_2 & \quad x_1 := x_1 - x_3 & \quad \max_{x \in X} x_0 = (x_1 - x_3) + x_2 \\ X = \left\{ \begin{aligned} &x_1 + x_2 \leq 4 \\ &x_1 - x_1 + x_2 \leq 2 \\ &x_1 \in R, x_2 \geq 0 \end{aligned} \right\} & \quad \longrightarrow & \quad X = \left\{ \begin{aligned} &x_1 + x_2 - x_3 \leq 4 \\ &x_1 - x_1 + x_2 + x_3 \leq 2 \\ &x \geq 0 \end{aligned} \right\} \end{aligned}$$

The basic, optimal solution: $\hat{x} = [x_1, x_2, x_3]^T = [0, 0, 2]^T \longrightarrow \hat{x} = [x_1, x_2]^T = [-2, 0]^T$

The optimal, objective function: $\hat{x}_0 = -2$

The special case - the set of admissible solutions is empty

$$X = \emptyset$$

In the first phase of simplex method the algorithm could not construct the first, basic, admissible solution - because there is no admissible solution in this case of the linear programming problem.

Example: $\max_{x \in X} x_0 = \frac{1}{2}x_1 - x_2 - x_3$

$$X = \left\{ \begin{aligned} &\frac{1}{2}x_1 + 2x_2 + x_3 \leq 2 \\ &-\frac{1}{2}x_1 + 2x_2 - x_3 \geq 3, x \geq 0 \\ &x_2 - x_3 \leq 2 \end{aligned} \right\}$$

	$-x_1$	$-x_2$	$-x_3$
x_0	0	-1/2	1
x_1	2	-1/2	2
x_2	-3	1/2	-2
x_3	2	0	1

	$-x_3$	$-x_4$	$-x_5$
x_0	x	x	x
x_1	x	x	x
x_2	-1	0	1
x_3	x	x	x

From the assumption the variables are ≥ 0 but from (1) it leads to:

$$x_5 < 0$$

$$x_1, x_2, x_3, x_4, x_5, x_6 \geq 0$$

$$x_3 = -x_4 - 2x_5 - 1 \quad (1)$$

IV Linear programming problem LP

$$\min x_0 = c^T x$$

Under the constraints in the form:

$$Ax \geq b$$

$$x \geq 0$$

$$\dim x = [n \times 1], \dim c = [n \times 1]$$

$$\dim A = [m \times n]$$

$$\dim b = [m \times 1]$$

Canonical form of IV LP problem

$$\min x_0 = c^T x,$$

$$Ax \geq b,$$

$$x \geq 0,$$

$$\max -x_0 = -c^T x,$$

$$-A x + I_s x_s = -b,$$

$$x, x_s \geq 0,$$

Optimal solution of IV LP problem with dual simplex method

Theorem:

The basic admissible solution of the set of equations $Ax=b$ is an optimal solution of IV LP problem, if the following conditions will be fulfilled:

(i) Dual admissible condition:

$$y_{0j} \geq 0 \quad \text{dla } j \in R_N$$

(ii) Dual optimal condition:

$$y_{i0} \geq 0 \quad \text{dla } i \in \{1, \dots, m\}$$

Dual simplex algorithm for the over-equal linear constraints

Step1. (start). Let us find first dual basic, admissible solution.

The admissibility condition: if $y_{0j} \geq 0$ dla $j \in R_N$

Yes - go to Step 2, No - STOP.

Step2. (optimality condition). If $y_{i0} \geq 0$ for each $i = 1, \dots, m$?

• Yes - an actual solution is optimal.

• No - go to Step 3.

Step3. (the variable, which will remove from the base). Let us choose such variable x_{B_r} for which $y_{r0} < 0$.

The rule to select the variable x_{B_r} is as follows:

$$y_{r0} = \min_{j \in R_N} \{y_{rj} \mid y_{rj} < 0, r = 1, \dots, m\}$$

Go to Step 4.

Dual simplex algorithm

Step 4. (the variable, which will enter to the base). Let us choose such variable x_k

For which, the following relation is fulfilled:

$$\frac{y_{0k}}{y_{rk}} = \max \left(\frac{y_{0j}}{y_{rj}} \mid y_{rj} < 0 \right).$$

If some variables exist with this condition, let us choose only one arbitrary.

Go to Step 5.

Step 5. (Gauss method).

Calculate the dual simplex iteration with Gauss elimination method entering the variable x_k to the base and moving the variable x_{B_r} out from the base.

Let us substitute for a new basic, admissible solution.

Go to Step 2.

Example for the dual simplex method

$$\min_{x \in X} x_0 = 1x_1 + 1x_2$$

$$X = \{x \mid \begin{cases} +1x_1 + 2x_2 \geq 8 \\ +2x_1 + 1x_2 \geq 6, x \geq 0 \end{cases}\}$$

Initial table

	$-x_1$	$-x_2$	
$-x_0$	0	1	1
x_1	-8	-1	-2
x_2	-6	-2	-1
x_3	-5	-1	-1

Dual admissible table

$$y_{0j} \geq 0 \quad \text{dla } j \in R_N$$

Intermediate table

	$-x_1$	$-x_2$	
$-x_0$	-4	3/2	3/2
x_2	4	3/2	-1/2
x_3	-2	-3/2	-1/2
x_5	-1	-1/2	-1/2

Not yet optimal table

$$y_{20} < 0$$

$$y_{30} < 0$$

Intermediate table

	$-x_1$	$-x_2$	
$-x_0$	-14/3	1/3	1/3
x_2	10/3	1/3	-2/3
x_1	4/3	-2/3	1/3
x_5	-1/3	-1/3	-1/3

Not yet optimal

$$y_{30} < 0$$

Example for the dual simplex method

I optimal table

$$y_{i0} \geq 0 \quad \text{dla } \forall i=1, \dots, m$$

		$-x_5$	$-x_6$	
$-x_5$	-5	1	0	
x_2	3	1	-1	
x_1	2	-2	1	
x_6	1	-3	1	

II optimal table

		$-x_5$	$-x_6$	
$-x_5$	-5	1	0	
x_2	4	-2	1	
x_1	1	1	-1	
x_6	1	-3	1	

I extreme point: $\hat{x}^1 = [x_1^1, x_2^1, x_3^1, x_4^1, x_5^1] = [2, 3, 0, 1, 0]$
 II extreme point: $\hat{x}^2 = [x_1^2, x_2^2, x_3^2, x_4^2, x_5^2] = [1, 4, 1, 0, 0]$
 $\hat{x}_0 = 5$
 The set of optimal solutions: $\hat{x} = \{x: x = (1+\lambda), (4-\lambda), \lambda \in [0,1]\}$

Dual theory for linear programming problem LP

LP problem

$$\max x_0 = c^T x$$

$$A x \leq b$$

$$x \geq 0$$

Dual LP problem

$$\min v_0 = v^T b$$

$$A^T v \geq c$$

$$v \geq 0$$

Theorem 7.1 :

If a vector x is an admissible solution for LP problem and a vector v is an admissible solution for dual LP problem, then the optimal value of dual LP problem fulfills the following relation:

$$v^T b \geq c^T x$$

Dual theory for linear programming problem LP

Theorem 7.2

If one of the two problems: LP problem or dual LP problem has its optimal solution,

there the second problem has also its optimal solution $\hat{x}^i \hat{v}$ and two problems have the same objective function value.

$$c^T \hat{x} = b^T \hat{v}$$

Theorem 7.3

Let (x_r, x_s) i (v_r, v_s) be the admissible solutions for LP problem and dual LP problem in the canonical form of equations.

Then the complementary condition for variables in LP problem and dual LP problem will take the form as below:

$$\hat{x}_r^T \hat{v}_s = 0 \quad \implies \quad x_r^T v_s + x_s^T v_r = 0$$

Theorem 7.4

If dual LP problem is unlimited, then the LP problem is inconsistent.

Example I LP problem

$$\min_{\text{vef}} v_0 = 5v_1 + 0v_2 + 21v_3$$

$$V = \left\{ \begin{array}{l} v_1 - v_2 + 6v_3 \geq 2 \\ x: v_1 + v_2 + 2v_3 \geq 1 \\ v_1, v_2, v_3 \geq 0 \end{array} \right.$$

Solution vector:

$$v = [v_1, v_2, v_3] = [v_1, v_2, v_3/v_3]$$

$$x^T v = 0 \implies [x_1, x_2]^T [v_1, v_2, v_3] = 0$$

Dual LP problem

$$\max_{\text{zeX}} x_0 = 2x_1 + 1x_2$$

$$X = \left\{ \begin{array}{l} x_1 + x_2 \leq 5 \\ x: -x_1 + x_2 \leq 0, x \geq 0 \\ 6x_1 + 2x_2 \leq 21 \end{array} \right.$$

$$x = [x_1, x_2] = [x_1, x_2/x_1, x_2, x_1, x_2]$$

Example II Cutting stock problem

$$\min v_0 = 0.3v_1 + 0.6v_2 + 0.2v_3$$

$$7v_1 + 3v_2 + 0v_3 \geq 2100$$

$$0v_1 + 1v_2 + 2v_3 \geq 1200$$

$$v_1, v_2, v_3 \geq 0$$

$$\max_{\text{zeX}} x_0 = 2100x_1 + 1200x_2$$

$$X = \left\{ \begin{array}{l} 7x_1 + 0x_2 \leq 0.3 \\ x: 3x_1 + 1x_2 \leq 0.6, x \geq 0 \\ 0x_1 + 2x_2 \leq 0.2 \end{array} \right.$$

Dual theory for linear programming problem LP

I. Dual LP problem solution with simplex method

Dual LP problem: $\max_{\text{zeX}} x_0 = 2x_1 + 1x_2$ $X = \left\{ \begin{array}{l} 1x_1 + 1x_2 \leq 5 \\ x: -x_1 + x_2 \leq 0, x \geq 0 \\ 6x_1 + 2x_2 \leq 21 \end{array} \right.$

	x_1	x_2	
x_5	0	-2	-1
x_2	5	1	1
x_4	0	-1	1
x_6	21	6	2

	x_3	x_2	
x_5	7	1/3	-1/3
x_6	3/2	-1/6	2/3
x_4	7/2	1/6	4/3
x_1	7/2	1/6	1/3

	x_5	x_6	
x_5	31/4	1/4	1/2
x_6	9/4	-1/4	3/2
x_1	1/2	1/2	-2
x_1	11/4	1/4	-1/2

Optimal solution:

a) Dual LP problem $\hat{x} = [x_1, x_2, \uparrow x_3, x_4, x_5]$ $\hat{x} = \left[\frac{11}{4}, \frac{9}{4}, \uparrow 0, \frac{1}{2}, 0 \right]$
 b) LP problem $\hat{v} = [v_1, v_2, \uparrow v_3, v_4, v_5]$ $\hat{v} = \left[0, 0, \uparrow \frac{1}{2}, 0, \frac{1}{4} \right]$

Optimal value of the objective function $\hat{x}_0 = v_0 = \frac{31}{4}$